# Multiple-expectation Systems 

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## Outline

(1) Motivation

- Extension to Probabilistic B
- Background
(2) Our Results/Contribution
- Multiple Probabilistic Specification Substitutions
- Fundamental Theorem
- Case Study: Duelling Cowboys


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## Extending probabilistic B

- To extend the scope of probabilistic $B(p B)$ to cover systems with multiple probabilistic properties;
- Need to introduce multiple probabilistic specification substitution;
- Investigate the new substitution in the framework of layered developments.


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## How pGSL extends GSL

## Expectations replace predicates

Predicates (functions from state to Boolean) are widened to Expectations (functions from state to non-negative real).

- For consistency with Boolean logic, we use embedded predicates, $\langle$ false $\rangle=0$, and $\langle$ true $\rangle=1$. - Notationally, we have kept predicates as much as possible.


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- Notationally, we have kept predicates as much as possible.


## Probabilistic generalised substitution language

## Summary

$$
[x:=E] \exp
$$

The expectation obtained after replacing all free occurrences of $x$ in exp by $E$
[skip]exp
$\left[\right.$ prog $_{1} p \oplus$ prog $\left._{2}\right]$ exp
$\operatorname{prog}_{1} \sqsubseteq$ prog $_{2}$
[prog \| prog ${ }_{2}$ ]exp
[@y. pred $\Longrightarrow$ prog]exp
exp
$\begin{array}{ccc}p & \times & {\left[\text { prog }_{1}\right] \exp } \\ +(1-p) & \times & {\left[p r o g_{2}\right] \exp } \\ {\left[\operatorname{prog}_{1}\right] \exp } & \Rightarrow & {\left[\text { prog }_{2}\right] \exp } \\ {\left[\operatorname{prog}_{1}\right] \exp \min } & {\left[\text { prog }_{2}\right] \exp } \\ \min (y) \cdot(\text { pred } \mid[\text { prog }] \exp )\end{array}$

## Probabilistic generalised substitution language

## Summary

$$
\begin{aligned}
& {[x:=E] \exp \quad \text { The expectation obtained after re- }} \\
& \begin{array}{l}
\text { The expectation obtained after re- } \\
\text { placing all free occurrences of } x \text { in }
\end{array} \\
& \text { exp by } E \\
& \text { [skip]exp exp } \\
& {\left[\operatorname{prog}_{1} p \oplus \text { prog }_{2}\right] \text { exp }} \\
& \operatorname{prog}_{1} \sqsubseteq \operatorname{prog}_{2} \\
& \text { [prog \| prog }{ }_{2} \text { ]exp } \\
& \text { [@y. pred } \Longrightarrow \text { prog]exp }
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& {[x:=E] \exp \quad \text { The expectation obtained after re- }} \\
& \text { placing all free occurrences of } x \text { in } \\
& \text { exp by } E \\
& {\left[\operatorname{prog}_{1}{ }_{p} \oplus \text { prog }_{2}\right] \exp } \\
& p \times\left[\operatorname{prog}_{1}\right] \exp \\
& +(1-p) \times\left[\operatorname{prog}_{2}\right] \exp \\
& \text { prog }_{1} \sqsubseteq \text { prog }_{2} \\
& \text { [prog \| prog }{ }_{2} \text { ]exp } \\
& \text { [@y. pred } \Longrightarrow \text { prog]exp } \\
& {\left[\text { prog }_{1}\right] \text { exp } \Rightarrow\left[\text { prog }_{2}\right] \exp } \\
& \text { [prog } \left.{ }_{1}\right] \exp \min \left[\text { prog }_{2}\right] \exp \\
& \min (y) \cdot(p r e d \mid[p r o g] e x p)
\end{aligned}
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& {\left[\text { prog }_{1}\right] \exp \text { min }\left[\text { prog }_{2}\right] \exp } \\
& \text { min (y) ( pred | [prog]exp) }
\end{aligned}
$$

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& \text { [prog } \left.{ }_{1}\right] \text { exp min }\left[\operatorname{prog}_{2}\right] \exp \\
& \min (y) \cdot(\text { pred } \mid[p r o g] e x p)
\end{aligned}
$$

## (Single) Probabilistic specification substitution

## Syntax

$v:\{A, B\}$, where $A$ and $B$ are expectations over state $x$.

- $v \subseteq x$
- B can refer to the original state by using subscripted variables $x_{0}$. The expected value of $B$ over the set of final distributions is at least the expected value of $A$ over the initial distribution.


## Semantics

( $w$ is the set of unchanged variables, i.e. $x-v$ ). (Similar work can be seen in White[1996] and Yinc [2003])

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## Semantics

$$
[v:\{A, B\}] C \widehat{=} A \times\left[x_{0}:=x\right]\left(\Pi x \cdot\left(\frac{C}{B \times\left\langle w=w_{0}\right\rangle}\right)\right)
$$

( $w$ is the set of unchanged variables, i.e. $x-v$ ).
(Similar work can be seen in White[1996] and Ying[2003])

## Fundamental theorem

## Probabilistic Theorem

Assume that prog $_{1} \widehat{=} v:\{A, B\}$.
For any program prog $_{2}$,

$$
\operatorname{prog}_{1} \sqsubseteq \operatorname{prog}_{2}
$$

if and only if

$$
A \Rightarrow\left[x_{0}:=x\right]\left[p r o g_{2}\right] B^{w},
$$

where $B^{w} \widehat{=} B \times\left\langle w=w_{0}\right\rangle$.

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## Multi-way probabilistic choice

For $i \in(1 . . n)$, let $p_{i}$ be a probabilistic expression over the state satisfying

$$
\begin{equation*}
\sum_{i=1}^{n} p_{i} \leq 1 \tag{1}
\end{equation*}
$$

Let $S_{i}$ be a probabilistic substitution. The multi-way probabilistic choice is defined as follows:

$$
\left[\begin{array}{ll}
S_{1} & @ p_{1}  \tag{2}\\
S_{2} & @ p_{2} \\
\cdots & \\
S_{n} & @ p_{n},
\end{array}\right] E \equiv \begin{aligned}
& \quad \begin{array}{l}
p_{1} \times\left[S_{1}\right] E \\
+ \\
p_{2} \times\left[S_{2}\right] E \\
+ \\
+ \\
+ \\
p_{n} \times\left[S_{n}\right] E
\end{array} .
\end{aligned}
$$

where $E$ is an arbitrary expectation of the state.

## Set of pre- and post-expectations

For $i \in(1 . . n)$, let $p_{i}$ be a probabilistic expression over the state $x$ and free from $x_{0}$ and satisfying:

$$
\begin{equation*}
\sum_{i=1}^{n} p_{i} \leq 1 \tag{3}
\end{equation*}
$$

let $Q_{i}$ be predicates defined over $x_{0}, v$ (where $v$ is a subset of $x$ ) and satisfying, for all $Q_{i}$, that we have

$$
\begin{equation*}
\forall x_{0} \cdot\left(\exists v \cdot Q_{i}\right) . \tag{4}
\end{equation*}
$$

## Semantics

Let $p_{0}=1-\sum_{i=1}^{n} p_{i}$, we define

$$
v: \left\lvert\, \begin{array}{l|ll}
\left\{p_{1},\left\langle Q_{1}\right\rangle\right\} & \left(v:\left\{1,\left\langle Q_{1}\right\rangle\right\}\right) & \varrho p_{1}  \tag{5}\\
\left\{p_{2},\left\langle Q_{2}\right\rangle\right\} & \left(v:\left\{1,\left\langle Q_{2}\right\rangle\right\}\right) & \varrho p_{2} \\
\cdots & \left(v:\left\{1,\left\langle Q_{n}\right\rangle\right\}\right) & \varrho p_{n} \\
\left\{p_{n},\left\langle Q_{n}\right\rangle\right\} & (x:\{1,1\}) & \varrho p_{0}
\end{array}\right.
$$

## Semantics

Let $p_{0}=1-\sum_{i=1}^{n} p_{i}$, we define

$$
v:\left|\begin{array}{l}
\left\{p_{1},\left\langle Q_{1}\right\rangle\right\}  \tag{5}\\
\left\{p_{2},\left\langle Q_{2}\right\rangle\right\} \\
\ldots \\
\left\{p_{n},\left\langle Q_{n}\right\rangle\right\}
\end{array} \quad \widehat{=}\right| \begin{array}{ll}
\left(v:\left\{1,\left\langle Q_{1}\right\rangle\right\}\right) & \varrho p_{1} \\
\left(v:\left\{1,\left\langle Q_{2}\right\rangle\right\}\right) & \varrho p_{2} \\
\cdots & \left(v:\left\{1,\left\langle Q_{n}\right\rangle\right\}\right) \\
\varrho p_{n} \\
(x:\{1,1\}) & \varrho p_{0} .
\end{array}
$$

## Examples

## A fair coin

$$
S_{1} \hat{=} c: \begin{align*}
& \left\{\frac{1}{2},\langle c=H\rangle\right\}  \tag{6}\\
& \left\{\frac{1}{2},\langle c=T\rangle\right\}
\end{align*}
$$

## A non－deterministic coin：

A coin which guarantees to return Heads at least $1 / 3$ of the time and Tails at least $1 / 3$ of the time．

## Examples

## A fair coin

$$
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\end{align*}\right.
$$

## A non-deterministic coin:

A coin which guarantees to return Heads at least $1 / 3$ of the time and Tails at least $1 / 3$ of the time.

$$
S_{2} \hat{=} c: \left\lvert\, \begin{align*}
& \left\{\frac{1}{3},\langle c=H\rangle\right\}  \tag{7}\\
& \left\{\frac{1}{3},\langle c=T\rangle\right\}
\end{align*}\right.
$$

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We consider a special set of multiple probabilistic specification substitutions where for any pair $Q_{i}$ and $Q_{j}$, where $i \neq j$, we have

$$
\begin{equation*}
Q_{i} \wedge Q_{j}=\text { false } \tag{8}
\end{equation*}
$$

## Probabilistic Theorem

For all programs $T$, if

$$
\begin{array}{rlll}
(x:\{1,1\}) & \sqsubseteq & T \text { and } \\
\left(v:\left\{p_{i},\left\langle Q_{i}\right\rangle\right\}\right) & \sqsubseteq & T, & \text { for all } i \in(1 \ldots n), \tag{10}
\end{array}
$$

then we have

$$
v: \left\lvert\, \begin{array}{llll}
\left\{p_{1},\left\langle Q_{1}\right\rangle\right\} & &  \tag{11}\\
\left\{p_{2},\left\langle Q_{2}\right\rangle\right\} & \sqsubseteq & \sqsubseteq & T . \\
\ldots & \left\{p_{n},\left\langle Q_{n}\right\rangle\right\} & &
\end{array}\right.
$$

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## Two cowboys

## Conditions

There are two cowboys $X$ and $Y$ fighting a duel. They take turns to shoot at each other.

- The probability for $X$ to hit his opponent is $\frac{2}{3}$.
- The probability for $Y$ to hit his opponent is $\frac{1}{2}$.
- Assuming that $X$ has the advantage of shooting first.


## Question?

What are the guaranteed survival probabilities for both cowboys?

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## Question?

What are the guaranteed survival probabilities for both cowboys?

## Formal specification

Let $p_{X}$ and $p_{Y}$ be the survival probability for $X$ and $Y$, respectively. Let $s$ be the cowboy which survives the duelling.

## Specification

$s \longleftarrow$ TwoCowboyXYSpec $\hat{=} s: \left\lvert\, \begin{aligned} & \left\{p_{X},\langle s=X\rangle\right\} \\ & \left\{p_{Y},\langle s=Y\rangle\right\}\end{aligned}\right.$

## Implementation

$s \longleftarrow$ TwoCowboyXYImp $\widehat{=}$ VAR $t, n$ IN


END
EXPECTATIONS
END

## Case Study: Duelling Cowboys

## Implementation

$s \longleftarrow$ TwoCowboyXYImp $\widehat{=}$ VAR $t, n$ IN

$$
t:=X ; s:=X ; n:=2 ; \quad / / \text { init }
$$

 IF $t=X$ THEN
$\qquad$

END


END

## Implementation

$$
\begin{aligned}
& s \longleftarrow \text { TwoCowboyXYImp } \widehat{=} \\
& \text { VAR } t, n \text { IN } \\
& t:=X ; s:=X ; n:=2 ; \\
& \text { WHILE } n=2 \text { DO // Loop }
\end{aligned}
$$

$\square$

END

## Case Study: Duelling Cowboys

## Implementation

$s \longleftarrow$ TwoCowboyXYImp $\widehat{=}$
VAR $t, n$ IN
$t:=X ; s:=X ; n:=2$;
WHILE $n=2$ DO

$$
\begin{aligned}
& \text { IF } t=X \text { THEN } / / \text { body } \\
& \quad(s:=X ; n:=1) \quad \frac{2}{3} \oplus \quad t:=Y
\end{aligned}
$$

## ELSE

$$
(s:=Y ; n:=1) \quad \frac{1}{2} \oplus \quad t:=X
$$

END
EXPECTATIONS...
END
END

## Proof obligations

In order to prove that TwoCowboyXYSpec $\sqsubseteq$ TwoCowboyXYImp, we have to prove that

$$
\begin{equation*}
\left(s:\left\{p_{X},\langle s=X\rangle\right\}\right) \sqsubseteq \text { TwoCowboyXYImpl } \tag{12}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(s:\left\{p_{Y},\langle s=Y\rangle\right\}\right) \sqsubseteq \text { TwoCowboyXYImpl . } \tag{13}
\end{equation*}
$$

Then we can apply the fundamental theorem for single probabilistic specification substitution for (12) and (13) separately. For (12) we have to prove that

$$
\begin{equation*}
p_{X} \Rightarrow[\text { init; Loop }]\langle s=X\rangle \tag{14}
\end{equation*}
$$

## Recall proof rules for probabilistic loops

For a probabilistic loop, such as

$$
\text { loop } \widehat{=} \text { while } G \text { do } S_{\text {invariant }} / \text { Expectation } E \text { end }
$$

then $A \Rightarrow \quad[$ init; loop $] B$ holds if the following satisfies:

| $P 1$ | $A$ | $\Rightarrow$ | $[$ init $] E$ |
| ---: | ---: | ---: | :--- |
| $P 2$ | $\langle G \wedge I\rangle * E$ | $\Rightarrow$ | $[S] E$ |
| $P 3$ | $\langle\neg G \wedge I\rangle * E$ | $\Rightarrow$ | $B$ |

(Here, I only concentrate on the maintenance of the expectation $E$ )

## Tabular method

For proving (14), we try to "guess" the expectation of the loop by tabulating the probabilities of establishing the post-expectation $s=X$ after executing one iteration of the loop.

|  | $n=2$ | $s=X \wedge n=1$ | $s=Y \wedge n=1$ |
| :---: | :---: | :---: | :---: |
| $t=X$ | $4 / 5$ | 1 | 0 |
| $t=Y$ | $2 / 5$ | 1 | 0 |

We have the expectation of the loop is

$$
\begin{equation*}
E \widehat{=}\langle s=X \wedge n=1\rangle+\langle n=2 \wedge t=X\rangle \times \frac{4}{5}+\langle n=2 \wedge t=Y\rangle \times \frac{2}{5} . \tag{15}
\end{equation*}
$$

Apply the proof rule $P$ 1, we need to prove that

$$
\begin{equation*}
p_{X} \Rightarrow[t:=X ; s:=X ; n:=2] E \tag{16}
\end{equation*}
$$

which is equivalent to

$$
\begin{equation*}
p_{X} \Rightarrow \frac{4}{5} . \tag{17}
\end{equation*}
$$

So we can choose $p_{X} \equiv \frac{4}{5}$, which will be the guaranteed surviving probability for $X$. With similar reasoning, we have $p_{Y} \equiv \frac{1}{5}$.

## Development in layers

## Three Cowboys

Assume that we have another cowboy, namely $Z$ with the probability of hitting his opponent is $\frac{1}{3}$. With similar setting, what are the surviving probabilities for the cowboys.

Here, we can use the specification of the two cowboys situation when write the implementation, for example, the case when $Y$ has the turn to shoot can be specified as follows:

$$
\begin{aligned}
& \text { IF } t=Y \text { THEN } \\
& \quad(s \longleftarrow \text { TwoCowboyXY; } n:=1) \quad_{\frac{1}{2}}+\quad t:=Z \\
& \text { ELSE } \cdots
\end{aligned}
$$

and the reasoning can be done similarly as in the case for two cowboys.

## Summary

- Abstractly specify and refine probabilistic systems with multiple properties.
- Development of these systems can be separated into layers.
- When the state is small, the expectation for loops can be found using the tabular method.


## For further reading I

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